

Generalised Reliability On Hydro-Geo Objects

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Abstract: This study established the fuzzy logic modeling of the stochastic finite element method based on the first-order approximation theorem. Fuzzy mathematical models of safety repertoires were incorporated into the stochastic finite element method to analyze the stability of embankments and foundations in order to describe the fuzzy failure procedure for the random safety performance function. The fuzzy models were developed with membership functions with half depressed gamma distribution, half depressed normal distribution, and half depressed echelon distribution. The result shows that the middle region of the dike is the principal zone of concentrated failure due to local fractures. There is also some local shear failure on the dike crust. This study provides a referential method for solving complex multi-uncertainty problems in engineering safety analysis.

Keywords: Approximation algorithm, stochastic finite element method, fuzzy membership, dike reliability.

1. INTRODUCTION

Stability research on geo-structures, which has undergone a historical progression from the safety factor K analysis phase to the reliability JC application phase, has now entered a hybrid theoretical research period (Yang and Zhao 1999; Lü and Feng 1997) [1-2] in which probabilistic theorems and fuzzy mathematics are introduced into general numerical algorithms. Chinese scholars such as Chen and Liu (1990) [3] and Wang and Chen (1996) [4] offer some original achievements in this area. Though there is an essential difference between fuzziness and randomness of engineering phenomena, the fuzziness and randomness both belong to generalized uncertainty and infiltrate each other. According to the definition of the probability theory, random phenomena and their probability might be deterministic or fuzzy. Thus, fuzzy probability is formed. Based on these facts, geo-engineering subjects should be investigated comprehensively with fuzzy mathematical theory and the probabilistic analytical theorem.

Safety of structures is predominated by generalized loading and resistance. Therefore, generalized safety characteristics of structures can be simulated from dual perspectives. One is the fuzziness of structure strength and loading, which can be studied with the definition of relevant fuzzy membership function, and the other is fuzzy deduction of structure working behavior, which, instead of arbitrary subjectivities, is derived from the fact that work behavior of structures often shows intrinsic fuzzy characteristics in a state between safety and failure. The fuzzy characteristics can be simulated with fuzzy numerical techniques, i.e., softening techniques. With fuzzy softening techniques, the

work behavior of structures is translated as a fuzzy event expressed by a generalized membership function M that is a fuzzy subset submitting to state space of structures. In terms of deduction of structures' working behavior, there are two approaches for practical engineering: the fuzzy definition of the safety margin and the fuzzy definition of the safety ratio. In this study, the fuzzy processing of embankment working behavior is carried out with first-order stochastic approximation and the harmonious finite element (HFE) theorem, by which numerical simulation of fuzzy-stochastic uncertainties of the embankment system of the Yangtze River in the southern Jingzhou zone of China is realized.

The theoretical model described here has been applied to the calculation of fuzzy random generalized reliability of the main embankment of the Yangtze River in the southern Jingzhou zone of China. The main embankment of the Yangtze River in the southern Jingzhou zone plays a significant role in flood control of the Yangtze River Valley. Its distinguished characteristics, such as its great span length and complicated geological strata, certify the substantial value of this research.

2. HARMONIOUS FINITE ELEMENT (HFE) FIRST-ORDER STOCHASTIC APPROXIMATION ALGORITHM

As for the conventional finite element method, the governing equation, on the basis of the minimum potential energy principle, can be formulated as (Zhuo 2000) [5].

$$\Pi_p = \frac{1}{2} \delta^T \mathbf{K} \delta - \delta^T \mathbf{Q}, \quad \mathbf{K} \delta = \mathbf{Q}, \quad \mathbf{Q} = \int_v \mathbf{N}^T f dv + \int_s \mathbf{N}^T p ds \quad (1)$$

where Π_p is the total potential energy, δ is the generalized displacement array, \mathbf{K} is the stiffness matrix, \mathbf{Q} is the

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equivalent nodal load array, N is the shape function interpolation matrix, f is the body force array, p is the surface load array, v is the spatial domain, and s is the surface domain. In practical engineering problems, K and Q are usually the functions of stochastic variable vector $X = \{x_1, x_2 \dots x_n\}$. So, should be deduced as a function of $X = \{x_1, x_2 \dots x_n\} : \delta = \delta(x_1, x_2 \dots x_n)$. There have been many numerical algorithms that treat the randomness of X (Lü and Feng 1997; Chen and Liu 1990; Wang and Chen 1996; Zhuo 2000; Christian and Baecher 1999) [2-6]. The first-order approximation theorem is applied here to expand the δ into a Taylor series around the mean values of X (Yang and Zhao 1999; Lü and Feng 1997)[1, 2]. In this study, the linear first-order expansion was adopted. The expectation of the generalized displacement array δ can be expressed in the following equation:

$$E(\delta) = E[\delta(x_1, x_2, \dots, x_n)] + \frac{\partial \delta}{\partial X} \cdot \left\{ (x_1 - \bar{x}_1), (x_2 - \bar{x}_2), \dots, (x_n - \bar{x}_n) \right\}^T = \delta(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n) \quad (2)$$

where $E(\delta)$ is the mathematical expectation of δ and $\bar{x}_i (i=1, 2, \dots, n)$ is the even value of an algorithm model variable. When the nodal value of the generalized displacement array is expressed as $\delta_i (i=1, 2, \dots, m)$, with m representing the node number of the corresponding numerical model, we have

$$\begin{aligned} V_{ar}(\delta_i) &= E \left\{ \left[E(x_i) - \bar{x}_i \right]^2 \right\} \\ &= E \left\{ \left[\sum_{k=1}^n (x_k - \bar{x}_k) \left(\frac{\partial \delta_i}{\partial x_k} \right) \right]^2 \right\} \\ &= \sum_{k=1}^n \sum_{l=1}^n \left(\frac{\partial \delta_i}{\partial x_k} \right) \left(\frac{\partial \delta_i}{\partial x_l} \right) E \left[(x_k - \bar{x}_k) \times (x_l - \bar{x}_l) \right] \\ &= \sum_{k=1}^n \sum_{l=1}^n \left(\frac{\partial \delta_i}{\partial x_k} \right) \left(\frac{\partial \delta_i}{\partial x_l} \right) C_{ov}(x_k, x_l) \end{aligned} \quad (3)$$

where $V_{ar}(\delta_i)$ is the variance of δ_i , $C_{ov}(x_k, x_l)$ is the covariance of x_k and x_l , and $\frac{\partial \delta_i}{\partial x_k}$ and $\frac{\partial \delta_i}{\partial x_l}$ are the partial derivatives of generalized nodal displacement δ_i with respect to x_k and x_l at the mean value of X . Similarly, in the harmonious finite element algorithm, the stress vector σ is also a function of random variable X : $\sigma = \sigma(x_1, x_2 \dots x_n)$. When the element stress is expressed as $\sigma_i = \sigma_i(x_1, x_2 \dots x_n)$, its corresponding variance as well as covariance can be formulated as follows (An *et al.* 2002) [7]:

$$\begin{aligned} V_{ar}(\sigma_i) &= \sum_{k=1}^n \sum_{l=1}^n \left(\frac{\partial \sigma_i}{\partial x_k} \right) \left(\frac{\partial \sigma_i}{\partial x_l} \right) C_{ov}(x_k, x_l) C_{ov}(\sigma_i, \sigma_j) \\ &= \sum_{k=1}^n \sum_{l=1}^n \left(\frac{\partial \sigma_i}{\partial x_k} \right) \left(\frac{\partial \sigma_j}{\partial x_l} \right) C_{ov}(x_k, x_l) \end{aligned} \quad (4)$$

For further information on Eq. 4, one can refer to related work (Christian and Bacher 1999; An *et al.*, 2002; Xu 2001) [6-8] that has offered the key algorithms for $\partial \sigma_1 / \partial x_k$, $\partial \sigma_2 / \partial x_k$, and $\partial \tau_{max} / \partial x_k$. Based on the content of the cited research, variance and covariance values of normal stress and maximal shear stress can be obtained from Eq. 4. Moreover, because the influence of structure body force is of great importance to stochastic numerical models for geo-engineering (Xu 2001) [8], the random vector Q in Eq. 1 is also a function of X .

3. RANDOM MODEL FOR LOCAL FAILURE OF HETEROGENEOUS STRUCTURE

Analyzed here is the local failure probability of an isotropic heterogeneous geo-structure without a predominant discontinuous slip crack interlayer. The failure probability under shear deformation and tensile deformation was calculated with the Mohr-Coulomb failure criterion. The strength characteristics of geo-material mainly include cohesive force c and internal friction angle ϕ . Owing to the intrinsic stochastic discreteness of survey data of c and ϕ , c and ϕ can be regarded as random variables (Chowdhury and Xu 1995; Guo and Wen 1992) [9,10]. Two principal safety reserve models are adopted in this study. They are the shear model q_s and the tensile model q_t , whose expressions are as follows:

$$\begin{aligned} q_s &= \tau_f - \tau_{max} \\ &= c \cos \phi + 0.5(\sigma_1 + \sigma_2) \sin \phi - 0.5(\sigma_1 - \sigma_2) \\ q_t &= \sigma_2 \end{aligned} \quad (5)$$

where τ_f and τ_{max} are, respectively, the distance from the center of the Mohr stress circle to the limiting failure line and the radius of the stress circle, and σ_1 and σ_2 are the maximum principal stress and intermediate principal stress, respectively.

It can be inferred from the foregoing analysis that q_s and q_t are stochastic variables. Therefore, their expectations and variances are formulated by the following equations:

$$\begin{aligned} E(q_s) &= E(c) \cos[E(\phi)] + 0.5[E(\sigma_1) + E(\sigma_2)] \cdot \sin[E(\phi)] - 0.5[E(\sigma_1) - E(\sigma_2)] \\ E(q_t) &= E(\sigma_2) \end{aligned} \quad (6)$$

$$\begin{aligned} V_{ar}(q_s) &= \left(\frac{\partial q_s}{\partial c} \right)^2 V_{ar}(c) + \left(\frac{\partial q_s}{\partial \phi} \right)^2 V_{ar}(\phi) + \left(\frac{\partial q_s}{\partial c} \right) \left(\frac{\partial q_s}{\partial \phi} \right) C_{ov}(c, \phi) + \sum_{k=1}^n \left(\frac{\partial q_s}{\partial x_k} \right) \left(\frac{\partial q_s}{\partial c} \right) C_{ov}[x_k, c] + \end{aligned}$$

$$\sum_{k=1}^n \left(\frac{\partial q_s}{\partial x_k} \right) \left(\frac{\partial q_s}{\partial \phi} \right) C_{ov} [x_k, \phi] +$$

$$\sum_{k=1}^n \sum_{l=1}^n \left(\frac{\partial q_s}{\partial x_k} \right) \left(\frac{\partial q_s}{\partial x_l} \right) C_{ov} [x_k, x_l]$$

$$V_{ar}(q_t) = \sum_{k=1}^n \sum_{l=1}^n \left(\frac{\partial \sigma_2}{\partial x_k} \right) \left(\frac{\partial \sigma_2}{\partial x_l} \right) C_{ov}(x_k, x_l) \quad (7)$$

4. FUZZY STOCHASTIC FAILURE MODEL OF HETEROGENEOUS STRUCTURE

With the Mohr-Coulomb failure criterion and limiting equilibrium theorem, the safety factor of a heterogeneous geo-structure can be defined as follows:

$$F_s = \frac{E(\tau_f)}{E(\tau_{max})}$$

$$= \frac{E(c) \cos[E(\phi)] + 0.5[E(\sigma_1) + E(\sigma_2)] \sin[E(\phi)]}{0.5[E(\sigma_1) - E(\sigma_2)]} \quad (8)$$

The reliability index is used to evaluate the random working behavior of geo-structures (Hassan and Wolff 1999; Low *et al.* 1998) [11,12]. Based on the assumption that q_s and q_t submit to Gaussian distribution, the reliability index can be expressed as $\beta = \mu_{q_s} / \sigma_{q_s}$, where μ_{q_s} and σ_{q_s} are, respectively, the even value and mean-square deviation of q_s .

The general failure probability P_f of geo-structures can be formulated as follows:

$$P_f = P(Z < 0) = \int_{-\infty}^0 \frac{1}{\sqrt{2\pi}\sigma_z} \exp \left[-\frac{1}{2} \left(\frac{z - \mu_z}{\sigma_z} \right)^2 \right] dz \quad (9)$$

where Z is the status function of geo-structures; σ_z and μ_z are, respectively, the mean-square deviation and even value of the status function Z ; and z is the probabilistic integration variable whose span is determined by Z . The generalized membership function M of geo-structure working behavior is expressed in Zadeh notation as Eq. 10, which, as softening technology, can realize the fuzzy formulation of the safety

reserve model:

where $g(X)$ is the status function, $\mu_M [g(X)]$ is the membership, and Ω is the fuzzy coverage.

$$M = \int_{\Omega} \frac{\mu_M [g(X)]}{X} \quad (10)$$

Based on the extension principle, the descriptions of failure probability and reliability index, P_f^* , the fuzzy-stochastic failure probability of geo-structure local deformation can be expressed as

$$P_f^* = \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}\sigma_{q_s}} \mu_M(q_s) \exp \left[-\frac{1}{2} \left(\frac{q_s - \mu_{q_s}}{\sigma_{q_s}} \right)^2 \right] dq_s \quad (11)$$

where all parameters are defined based on the q_s status function of geo-structures: σ_{q_s} and μ_{q_s} are, respectively, the mean-square deviation and even value of the status function q_s , and $\mu_M(q_s)$ is the fuzzy-stochastic membership.

Furthermore, in order to better analyze the embankment slope failure model, the comprehensive safety ratio R_s is defined as (Wang 2004) [13].

$$R_s = \frac{q_s}{0.5(\sigma_1 - \sigma_2)} = \frac{\tau_f - \tau_{max}}{\tau_{max}} = \frac{\tau_f}{\tau_{max}} - 1. \quad (12)$$

Uniting foregoing contents, the membership functions of three fuzzy models are shown in Table 1.

5. FUZZY STOCHASTIC NUMERICAL ALGORITHM APPLICATION TO EMBANKMENT STRUCTURE

In this study, in order to investigate the random working behavior of the geotechnical structure, a typical section 580+500 of the main embankment of the Yangtze River in the southern Jingzhou zone of China was analyzed with the local failure model using the fuzzy stochastic numerical algorithm.

Fig. (1) shows the cross section of the dike structure. The dike structure is divided into three stuff-fill zones whose

Table 1. Membership functions of three fuzzy models.

Fuzzy models	Membership functions
Half depressed gamma distribution	$\mu_M(R_s) = \begin{cases} 1 & R_s \leq -0.08 \\ \exp[-8.66 \times (R_s + 0.08)] & R_s \geq -0.08 \end{cases}$
Half depressed normal distribution	$\mu_M(R_s) = \begin{cases} 1 & R_s \leq -0.08 \\ \exp[-108.3 \times (R_s + 0.08)^2] & R_s \geq -0.08 \end{cases}$
Half depressed echelon distribution	$\mu_M(R_s) = \begin{cases} 1 & R_s \leq -0.08 \\ \frac{0.5 - R_s}{0.5 + 0.08} & -0.08 < R_s \leq 0.5 \end{cases}$

Table 2. Material properties of dike body.

Zone	E (MPa)	ν	ρ (10^6 g m^{-3})	c (kPa)	ω ($^\circ$)
1	4.1	0.3	1.41	15	18
2	2.8	0.25	1.55	21.6	21
3	14	0.1	1.64	0	31

material parameters are shown in Table 2.

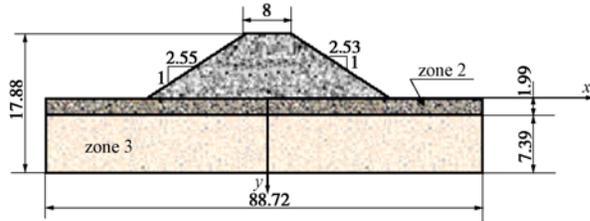


Fig. (1). Cross section of the dike structure (m).

Under gravitational body loading, the numerical model grid, whose boundary limit runs 19.4 m away from the upstream dike-ankle and 18.3 m away from the downstream dike-toe, has 275 elements and 174 nodes. It is assumed that the material parameters are statistically independent. Covariance matrixes of random parameters of three material zones are reduced to diagonal matrixes (Schweiger *et al.* 2001) [14] and the principal diagonal elements are the following:

$$\text{diag}(C_{ov_1})=(0.50,0.24,0.30,0.44,0.17)$$

$$\text{diag}(C_{ov_2})=(0.32,0.24,0.30,0.14,0.17)$$

$$\text{diag}(C_{ov_3})=(0.15,0.24,0.13,0.44,0.21)$$

Fig. (2) presents the deformed grid of a typical section under loading and it is evident that the stress concentration zone is in the middle region of embankment body. The latter displacement contour figures and stress contour figures (Fig. (3), Fig. (5), Fig. (7), and Fig. (8) demonstrate this fact as well.



Fig. (2). Sketch of mean deformations of dam mesh.

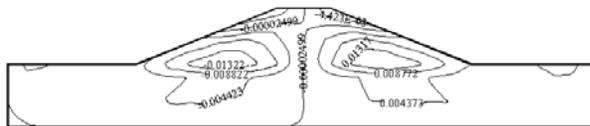


Fig. (3). Contours of mean of x -displacement in embankment section (m).

From Fig. (3) it can be deduced that the maximum gradient variation of the x displacement accumulates in the middle region of the embankment system, which is consistent with monitoring information (Wang 2004) [13]. Furthermore, some cracks almost break through the whole

dike crown on the local embankment sections. There are two reasons for this. The first is continual hydraulic scouring and random oscillation of the predominant waterline that can be summarized as external hydraulic influence, and the second is intrinsic stochastic characteristics. Sandy soil layers occupy most of the geo-space of the main embankment of the Yangtze River in the southern Jingzhou zone. The embankment foundation has a small expectation value of y displacement and a high value of E . However, shear deformation occurs and a local seepage channel is formed in the middle region of the embankment system. They have often put the embankment system in danger. Therefore, the high probability of absolute collapse under embankment-base erosion deformation must receive more attention. The displacement variance contours Fig. (4) and Fig. (6) show a small magnitude of variation of the stochastic displacement field, by which it can be deduced that the variation of the random displacement field has a low sensitivity to stochastic turbulence of material parameters.

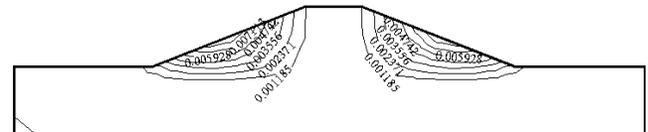


Fig. (4). Contours of variance of x -displacement in embankment section (m^2).

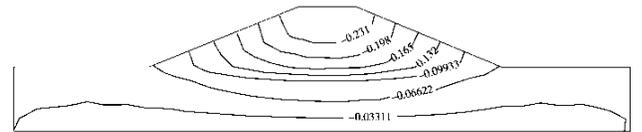


Fig. (5). Contour of mean of y -displacement in embankment section (m).

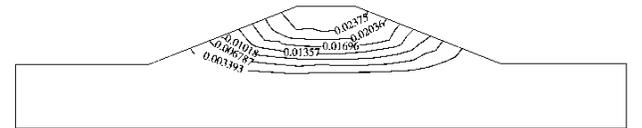
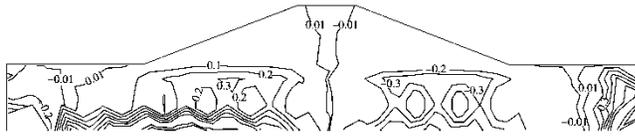


Fig. (6). Contour of variance of y -displacement in embankment section (m^2).

Random fluctuation of the stress field of the main embankment is shown in Figs. (7-10). The stress distribution shows great discreteness, and the stress variance is 10^2 times larger than the displacement variance in some regions. The high sensitivity of the stress field to random material parameters aggravates the stress concentration. Related research (Christian and Baecher 1999) [6] shows that these characteristics are consistent with the stochastic calculation results of q_s and q_t , and reveal potential danger in the local region of the embankment. Expectation values of the two principal safety reserve models are low enough to undermine

partial geo-zones, and this is demonstrated by on-the-spot investigation of the main embankment of the Yangtze River in the southern Jingzhou zone.



- (3) Softening technology is able to realize the fuzzy formulation of the safety reserve model that can analyze the uncertainty of the geo-structure working behavior. Three fuzzy mathematical models have been introduced in this study to comprehensively study generalized vector field characteristics.
- (4) The model calculation results indicate that the dike middle region is the principal concentrated failure zone, which is demonstrated by the on-the-spot investigation. Furthermore, there is also some local shear failure on the dike crust.

CONFLICT OF INTEREST

The authors confirm that this article content has no conflict of interest.

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